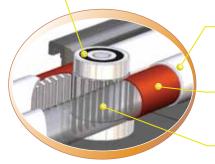




NARROW WIDTH AND LONG TRAVEL

ball bearings support pinion for smooth operation and long life



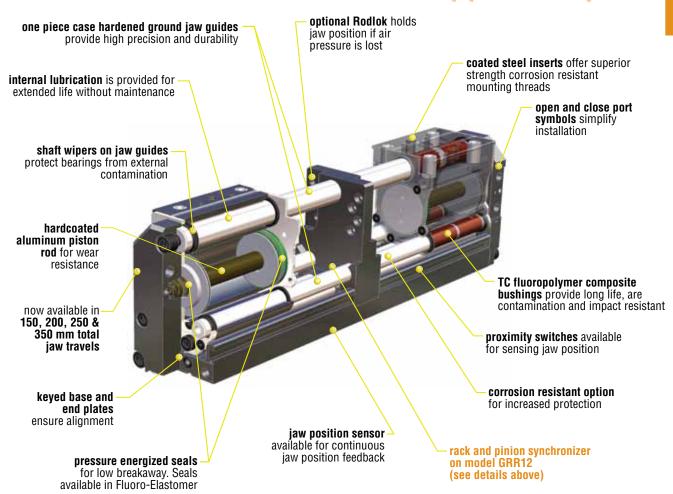
stainless tubing encloses rack to protect from contamination and to maintain lubrication

TC fluoropolymer composite bushings provide wear resistance

rack and pinion synchronizer minimizes backlash



GRR FEATURES











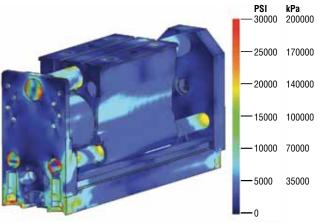
Design Enhancements

- 75% Higher moment capacity
- 55% Higher grip force
- 25% Higher speed
- 10% Lower weight
- · Additional accessories
- · Continuous feedback jaw position sensor
- Extensive engineering analysis and testing assure performance

Major Benefits

- Narrow width and a wide range of available jaw travels.
- Compact design provides high grip force and large moment capacities with low overall weight.
- Rugged build withstands high impact and shock loads.
- Double acting for both internal and external gripping.
- Unique dual air-passage piston rod design promotes rapid bore pressurization for short cycle times.
- Three large diameter jaw guides spanning the length of the gripper provide stable jaw travel, long allowable tooling length, and high moment capacities.
- TC fluoropolymer composite guide shaft bushings provide long life and smooth jaw travel in demanding industrial environments.
- Synchronizer is enclosed, protecting the mechanism from debris.
- Non-synchronized and independently controlled jaws allow flexibility to support diverse applications.
- Optional Rodlok locks the jaws in a stationary position in the event air pressure is lost.
- Optional analog output sensor continuously monitors entire jaw travel. Gripper is "sensor ready" for SPP99 option which allows the sensor to be factory installed or easily installed in the field. STT99 option cannot be added in the field and must be ordered in conjunction with the gripper.
- Proximity switches are available for discrete indication of jaw position.

STRESS ANALYSIS PLOT [psi]



(HALF MODEL SHOWN)

Industry Uses

- Material handling of rolls, barrels, pallets, and containers
- · Movement of large sand and investment castings
- · Small engine block manufacture
- Automotive, aeronautical, and agricultural wheel rim manufacture
- Clamping and fixturing during assembly operations
- · Gaging and sorting of large parts and assemblies
- · Centering and registration of heavy parts
- Incorporation into space-restricted processing and manufacturing equipment

List marks of PHD which appear on promotional material are registered trademarks of PHD, Inc.



ORDERING DATA: SERIES GRR GRIPPERS



- NPT Ports (metric units only) 19 H47

UNIT OPTIONS

- Rodlok (See Note 2)

- Fluoro-Elastomer Seals except for Rodlok mechanism

OPTIONS

(OMIT IF NOT REQUIRED)

PORT OPTIONS

- Corrosion resistant coating on exposed parts except for Rodlok mechanism and Rodlok rod

SENSOR OPTIONS

SPP99- Rotary jaw position sensor installed (see Note 3)

STT99 - Coupled rotary jaw position sensor installed (see Note 4)

OPTIONS (OMIT IF NOT REQUIRED) **JAW TRAVEL LIMITING OPTIONS GRR02, GRR12 & GRR22**

ANxxx - Jaw travel limitation on open, both jaws

ATxxx - Jaw travel limitation on closed, both jaws

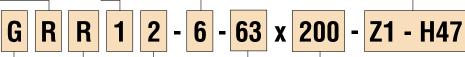
GRR02 & GRR22 ONLY

APxxx - Jaw travel limitation on open, Jaw A only

AQxxx - Jaw travel limitation on open, Jaw B only

ARxxx - Jaw travel limitation on closed, Jaw A only

AUxxx - Jaw travel limitation on closed, Jaw B only

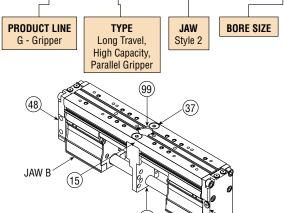


DESIGN NO.

(See Note 1)

2 - Imperial

6 - Metric



JAW A

Product Line, Series, Type, Synchronization, Jaw, Design No.,

0- Non-synchronized

2- Non-synchronized

1- Synchronized

SYNCHRONIZATION

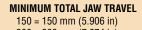
independently powered jaws

Size, Total Jaw Travel, and Options required.

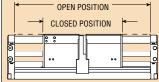
TO ORDER SPECIFY:

SERIES

Regular Duty



200 = 200 mm (7.874 in) 250 = 250 mm (9.843 in) 350 = 350 mm (13.780 in)



Total Jaw Travel = (Open position -**Closed Position)**

NOTES:

- 1) Design number indicates imperial or metric mounting holes and ports. Dowel pin holes are metric regardless of design number.
- 2) Standard unit is Rodlok ready.
- 3) Available on GRR1 only. GRR1 unit is SPP99 ready.
- 4) Available on GRR1 only. -STT99 option must be ordered with the gripper. Only sensor replacement kits are available.

SPP99 JAW POSITION SENSOR KITS

КІТ	STANDARD	CORROSION RESISTANT	
Sensor Replacement Kit	74209-31	74209-32	

Kit includes 1 jaw position sensor, 2 mounting screws, 1 seal and 1 coupling seal

8 mm & 12 mm THREADED INDUCTIVE PROXIMITY SWITCH TARGET KITS

STANDARD	CORROSION RESISTANT
74994-31	74994-32

Kit includes 1 proximity switch target and 2 target mounting screws

REPLACEMENT STT99 JAW POSITION SENSOR KITS

КІТ	STANDARD	CORROSION RESISTANT		
Sensor Replacement Kit	84404-11	84404-12		

Kit includes 1 jaw position sensor, 2 mounting screws, 1 seal and spring

THREADED INDUCTIVE PROXIMITY SWITCH MOUNTING BRACKET KITS

8 mm	CORROSION RESISTANT	12 mm	CORROSION RESISTANT								
SWITCH	8 mm SWITCH	SWITCH	12 mm SWITCH								
74992-3	74992-32	74993-31	74993-32								

Kit includes 1 proximity switch mounting bracket, 1 mounting nut, and 1 mounting screw

8 mm THREADED INDUCTIVE PROXIMITY SWITCHES

PART NUMBER	DESCRIPTION
51422-005-02	NPN (Sink), 2 meter cable
51422-006-02	PNP (Source), 2 meter cable

12 mm THREADED INDUCTIVE PROXIMITY SWITCHES

	PART NUMBER	DESCRIPTION
15561-001		NPN (Sink), 2 meter cable
	15561-002	PNP (Source), 2 meter cable
	15561-003	VAC Solid State, 3 meter cable



UNIQUE GRIPPERS ARE AVAILABLE. SEE PAGES 4-179 TO 4-204.



ENGINEERING DATA: SERIES GRR GRIPPERS

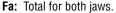


SPECIFICATIONS	SERIES GRR
OPERATING PRESSURE	
STANDARD UNIT	30 psi min to 120 psi [2 to 8 bar] max air
OPERATING TEMPERATURE	-20° to +180°F [-28° to +82°C]
	Higher temperature service available. Consult PHD.
RATED LIFE	5 million cycles minimum with standard seals
GRIP REPEATABILITY	Within ±0.002 in [±0.05 mm] of original centered position
CYCLE TIME	See table below
LUBRICATION	Factory lubricated for rated life
MAINTENANCE	Field repairable

MODEL	TOTA	IMUM Il Jaw Avel		PPER IGHT	CLOSE OR OPEN TIME 87psi [6 bar]	DIRE	NE CTION CEMENT	_	VARIES W	FACTOR GF VITH TOOLIN FILE INTERNA	G LENGTH
NUMBER	in	mm	lb	kg	sec	in ³	cm ³	IMPERIAL	METRIC	IMPERIAL	METRIC
GRRx2-x-63 x 150	5.91	150	28.0	12.7	0.28	28.8	472				
GRRx2-x-63 x 200	7.87	200	33.0	15.0	0.36	38.4	629	0.00	500	7.07	400
GRRx2-x-63 x 250	9.84	250	39.2	17.8	0.42	48.0	787	8.09	522	7.27	469
GRRx2-x-63 x 350	13.8	350	49.0	22.2	0.57	67.0	1098				

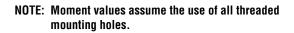
MAXIMUM ALLOWABLE FORCES AND MOMENTS

Ī	MODEL	Fa		M	K	Му	1	Mz	Mz	
	NUMBER	lb	N	in-lb	Nm	in-lb	Nm	in-lb	Nm	
	GRRx2-x-63 x 150	3500	15570	8000	880	6500	715	6500	715	
	GRRx2-x-63 x 200	3500	15570	9000	990	7500	825	7500	825	
	GRRx2-x-63 x 250	3500	15570	9000	990	7500	825	7500	825	
	GRRx2-x-63 x 350	3500	15570	9000	990	7500	825	7500	825	



Mx: Allowable moment per jaw, measured from jaw mounting surface.
My: Allowable moment per jaw, measured from geometric center of jaw.
Mz: Allowable moment per jaw, measured from jaw mounting surface.

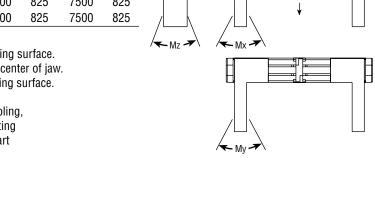
When calculating the value for Fa, include weight of tooling, part weight, acceleration, and external forces. When calculating values for Mx, My, and Mz, include the grip force per jaw, part weight, external forces, and acceleration as applicable.

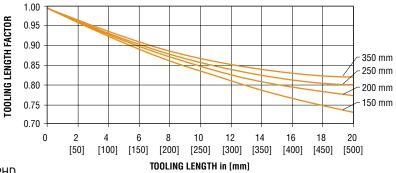


TOOLING LENGTH FACTOR

Jaw tooling should be designed so that the grip point is as close to the jaw surface as possible. As the grip point is moved away from the jaw surface, the applied moment causes jaw friction to increase, resulting in reduced effective grip force. The grip force factor $(G_{\scriptscriptstyle F})$ values given in the table above are for zero tooling length (jaw surface).

The maximum load that grippers can handle will vary based on: size of the part being picked up, shape of the part, texture of the part, speed at which the part is transferred, working pressure, shape of the fingers, etc. PHD recommends that the fingers of jaws be tooled or machined to conform to the shape of the part being gripped.





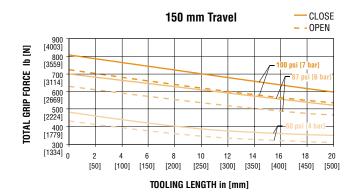


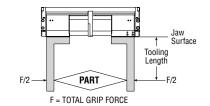
ENGINEERING DATA: SERIES GRR GRIPPERS

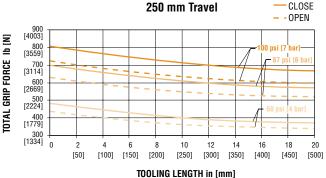


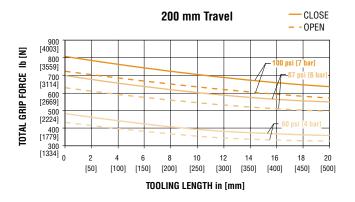
GRIP FORCE

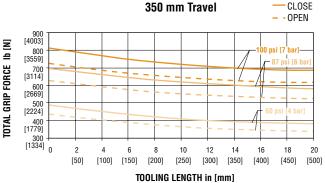
Total gripping force relative to tooling length is shown below at the stated actuating pressure. Grip force per jaw equals the total grip force divided by two. The graphs also indicate the maximum tooling length for each gripper size.











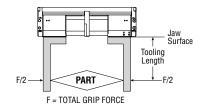
GRIP FORCE CALCULATION EQUATIONS:

IMPERIAL:

TOTAL GRIP FORCE [lb] = (Pressure [psi] \times G_F) \times Tooling Length Factor

METRIC:

TOTAL GRIP FORCE [N] = (Pressure [bar] \times G_F) \times Tooling Length Factor



GRIP FORCE CALCULATION EXAMPLE:

Gripper: Series GRR Size 63 x 200

Common Parameters:

Operating Pressure = 87 psi [6 bar] **Tooling Length** = 10 in [254 mm]

1. Determine Grip Force Factor $G_F = 8.09$ [522] (from table on page 4-94)

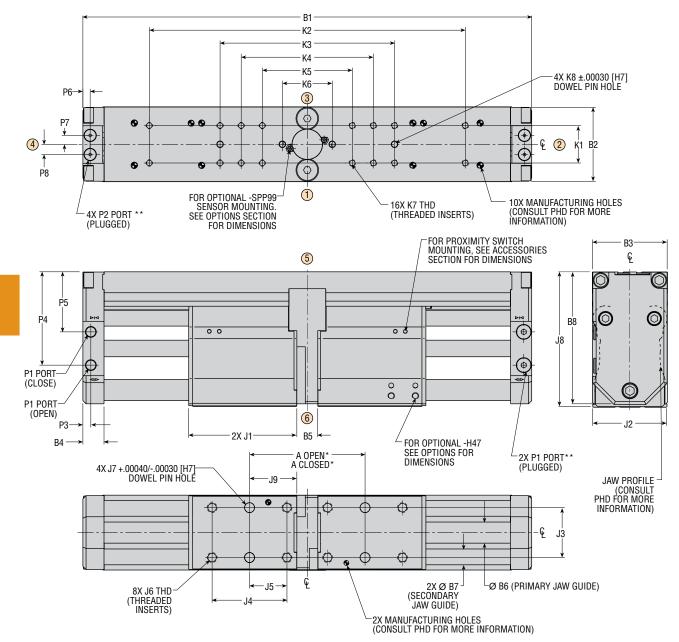
- 2. **Determine Tooling Length Factor =** 0.84 [0.84] (from Tooling Length Factor graph)
- 3. Total Grip Force Calculations:

For Standard Unit: GRR12-2-63 x 200 [GRR12-6-63 x 200]

Total Grip Force = 87 psi x 8.09 x 0.84 = 591 lb [6 bar x 522 x 0.84 = 2630 N]







NOTES:

- 1) DESIGNATED & IS CENTERLINE OF UNIT.
- 2) METRIC INFORMATION SHOWN IN [] OR SHOWN IN COLUMNS DESIGNATED mm.
- 3) CIRCLED NUMBERS INDICATE POSITION.
- 4) *A OPEN REFLECTS THE SMALLEST POSSIBLE OPEN DIMENSION. A CLOSED REFLECTS THE LARGEST POSSIBLE CLOSED DIMENSION.
- 5) **PLUGGED PORTS P1 & P2, CAN BE USED FOR GRIPPER ACTUATION.





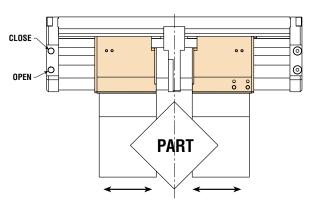
	MODEL NUMBER							
LETTER	GRRx2	-x-63 X 150	GRRx2	-x-63 X 200	GRRx2-	-x-63 X 250	GRRx2-	x-63 X 350
DIM	in	mm	in	mm	in	mm	in	mm
MIN. TRAVEL								
PER JAW	2.953	75.0	3.937	100.0	4.921	125.0	6.890	175.0
A CLOSED*	4.724	120.0	5.504	139.8	5.504	139.8	12.992	330.0
A OPEN*	10.630	270.0	13.379	339.8	15.347	389.8	26.772	680.0
B1	17.314	439.8	21.251	539.8	26.016	660.8	33.890	860.8
B2	3.500	88.9	3.500	88.9	3.500	88.9	3.500	88.9
В3	3.543	90.0	3.543	90.0	3.543	90.0	3.543	90.0
B4	1.000	25.4	1.000	25.4	1.000	25.4	1.000	25.4
B5	.990	25.1	.990	25.1	.990	25.1	.990	25.1
B6	1.000	25.4	1.000	25.4	1.000	25.4	1.000	25.4
B7	.750	19.1	.750	19.1	.750	19.1	.750	19.1
B8	6.250	158.8	6.250	158.8	6.250	158.8	6.250	158.8
J1	4.136	105.1	5.120	130.0	6.518	165.6	8.487	215.6
J2	3.500	88.9	3.500	88.9	3.500	88.9	3.500	88.9
J3	2.362	60.0	2.362	60.0	2.362	60.0	2.362	60.0
J4	2.598	66.0	3.544	90.0	3.544	90.0	3.544	90.0
J5	1.2990	33.0	1.7720	45.0	1.7720	45.0	1.7720	45.0
J6	1/2-13 x 1.00 DP	M12 x 1.75 x 25.0 DP	1/2-13 x 1.00 DP	M12 x 1.75 x 25.0 DP	1/2-13 x 1.00 DP	M12 x 1.75 x 25.0 DP	1/2-13 x 1.00 DP	M12 x 1.75 x 25.0 DP
J7	.47275 x .625 DP	12.0 x 15.9 DP	.47275 x .625 DP	12.0 x 15.9 DP	.47275 x .625 DP	12.0 x 15.9 DP	.47275 x .625 DP	12.0 x 15.9 DP
J8	6.375	161.9	6.375	161.9	6.375	161.9	6.375	161.9
J9	1.850	47.0	2.240	56.9	2.240	56.9	5.984	152.0
K1	1.773	45.0	1.773	45.0	1.773	45.0	1.773	45.0
K2	12.598	320.0	14.960	380.0	14.960	380.0	23.228	590.0
K3	8.260	209.8	8.260	209.8	8.260	209.8	8.260	209.8
K4	6.260	159.0	6.260	159.0	6.260	159.0	6.260	159.0
K5	4.260	108.2	4.260	108.2	4.260	108.2	4.260	108.2
K6	2.3620	60.0	2.3620	60.0	2.3620	60.0	2.3620	60.0
K7	3/8-16 x .750 DP	M8 x 1.25 x 19.0 DP	3/8-16 x .750 DP	M8 x 1.25 x 19.0 DP	3/8-16 x .750 DP	M8 x 1.25 x 19.0 DP	3/8-16 x .750 DP	M8 x 1.25 x 19.0 DP
K8	.31525 x .750 DP	8.0 x 19.0 DP	.31525 x .750 DP	8.0 x 19.0 DP	.31525 x .750 DP	8.0 x 19.0 DP	.31525 x .750 DP	8.0 x 19.0 DP
P1	1/4 NPT	1/4 BSPP						
P2	1/8 NPT	1/8 BSPP						
P3	.375	9.5	.375	9.5	.375	9.5	.375	9.5
P4	4.50	114.3	4.50	114.3	4.50	114.3	4.50	114.3
P5	3.250	82.6	3.250	82.6	3.250	82.6	3.250	82.6
P6	.344	8.7	.344	8.7	.344	8.7	.344	8.7
P7	.413	10.5	.413	10.5	.413	10.5	.413	10.5
P8	.591	15.0	.591	15.0	.591	15.0	.591	15.0





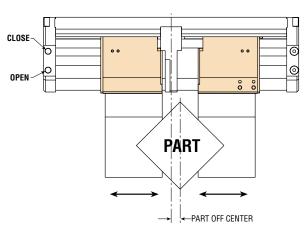
GRR12 SYNCHRONIZED

This model synchronizes the jaws for use with parts that must be centered. Jaws are pressurized by a single set of ports.



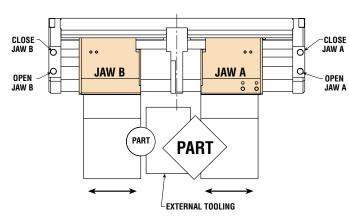
GRR02 NON-SYNCHRONIZED

This model allows each jaw to move independently while being pressurized by a single set of ports. This feature allows the gripping of off center parts.



NON-SYNCHRONIZED GRR22 AND INDEPENDENTLY **POWERED JAWS**

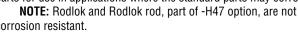
This model adds the ability to independently power each jaw. The jaws are not synchronized and may be cycled at differing rates or pressures.



CORROSION RESISTANT

This option provides a corrosion resistant coating on all ferrous parts for use in applications where the standard parts may corrode.

corrosion resistant.





METRIC UNIT WITH IMPERIAL (NPT) PORTS



FLUORO-ELASTOMER SEALS

Fluoro-elastomer seals and PTFE jaw guide scrapers are available to achieve seal compatibility with certain fluids. Seal compatibility should be checked with the fluid manufacturer for proper application.

NOTE: Rodlok (part of -H47 option) does not include -V1 components. Consult PHD for fluid compatibility with -STT99 and -SPP99 option. Consult PHD for high temperature use.



PHDV1



TRAVEL LIMITING STOPS

These options provide corrosion resistant jaw travel stop tubes for use in limiting jaw travel on open or close. The travel limiting stop tubes provide a repeatable positive stop.

Model GRR12 requires identical stops for both jaws while traveling in the same direction. Synchronized units may only use the ANxxx and ATxxx options. Non-synchronized models (GRR02 & GRR22) may use the APxxx, ARxxx, AUxxx, or AQxxx in any

combination for limiting the travel of either jaw independently.

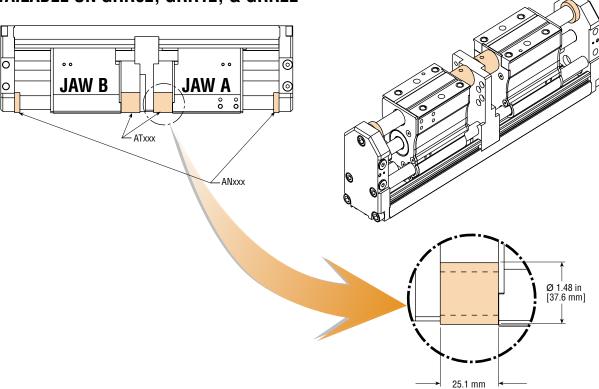
Non-synchronized units may also be ordered with ANxxx or ATxxx options.

Travel limiting tubes are available in lengths from 3.0 to 99.9 mm in .1 mm increments. See Note 2.

For adjustable jaw travel, see travel adjustment collars on page 4-145.



AVAILABLE ON GRR02, GRR12, & GRR22







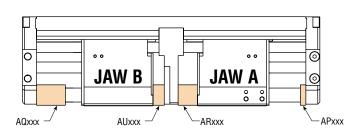




EXAMPLE:

-ATxxx stop with 25.1 mm length = -AT251

AVAILABLE ON GRR02 & GRR22 MODELS ONLY



NOTES:

- Options' xxx are in .1 mm increments with implied decimal point one place from right, and must be 3 digits long with values ranging between 03.0 and 99.9 mm.
- 2) ANxxx and ATxxx or APxxx and ARxxx or AUxxx and AQxxxx option combinations or singularly can not add up to more than 1/2 the ordered jaw travel.

Example for 150 mm jaw travel:

 $ANxxxx + ATxxx \le 75$

 $APxxxx + ARxxx \le 75$

 $AUxxxx + AQxxx \le 75$



RODLOK

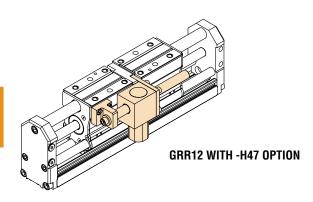
PHD's Rodlok is ideal for locking the jaws while in a static/ stationary position. When the pressure is removed from the port of the Rodlok, the mechanism will grip on the external guide shaft and prevent the jaws from moving. The loads are held indefinitely without power. Rodlok performance is application and environment sensitive. Cleanliness of shaft or Rodlok will also affect performance.

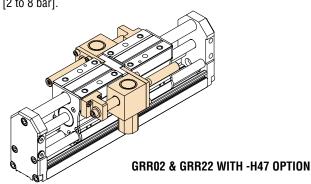
THE RODLOK IS NOT DESIGNED TO BE USED AS A PERSONNEL SAFETY DEVICE.

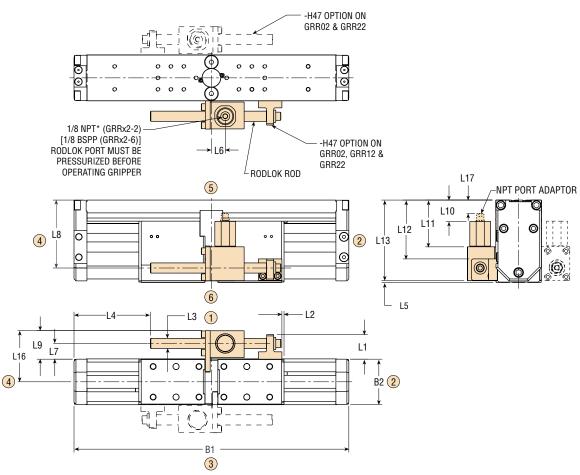
Option -H47 provides the Rodlok pre-assembled to the gripper. The port of the Rodlok device will be in position 5.

Option -H47 may be purchased with the -Z1 (corrosion resistant) option and -V1 (fluid compatibility) option. However the Rodlok and Rodlok rod DO NOT PROVIDE corrosion resistance or fluid compatibility.

OPERATING PRESSURE: The operating pressure for the locking device is different than the operating pressure for the gripper with the Rodlok attached. The locking device of the Rodlok is designed with an operating pressure range of 60 psi minimum to 150 psi maximum [4 to 10 bar]. The Series GRR Gripper with a Rodlok attached has an operating pressure range of 30 psi minimum to 120 psi maximum [2 to 8 bar].







OPTIONS & ACCESSORIES: SERIES GRR GRIPPERS



	MODEL NUMBER								
LETTER	GRRx2-x-63 X 150		GRRx2-x	GRRx2-x-63 X 200		GRRx2-x-63 X 250		GRRx2-x-63 X 350	
DIM	in	mm	in	mm	in	mm	in	mm	
B1	17.314	439.8	21.251	539.8	26.016	660.8	33.890	860.8	
B2	3.500	88.9	3.500	88.9	3.500	88.9	3.500	88.9	
L1	1.900	48.3	1.900	48.3	1.900	48.3	1.900	48.3	
L2	.165	4.2	.165	4.2	1.630	41.4	3.370	85.6	
L3	.787	20.0	.787	20.0	.787	20.0	.787	20.0	
L4	4.920	125.0	5.900	149.9	7.280	184.9	9.250	235.0	
L5	.141	3.6	.141	3.6	.141	3.6	.141	3.6	
L6	1.070	27.2	1.070	27.2	1.070	27.2	1.070	27.2	
L7	1.217	30.9	1.217	30.9	1.217	30.9	1.217	30.9	
L8	5.254	133.5	5.254	133.5	5.254	133.5	5.254	133.5	
L9	2.209	56.1	2.209	56.1	2.209	56.1	2.209	56.1	
L10	1.150	41.9	1.150	41.9	1.150	41.9	1.150	41.9	
L11	3.618	91.9	3.618	91.9	3.618	91.9	3.618	91.9	
L12	4.550	115.6	4.550	115.6	4.550	115.6	4.550	115.6	
L13	6.234	158.3	6.234	158.3	6.234	158.3	6.234	158.3	
L14	3.95 lb	1.79 kg	4.22 lb	1.91 kg	4.35 lb	1.97 kg	4.65 lb	2.11 kg	
L15	7.90 lb	3.58 kg	8.44 lb	3.83 kg	8.70 lb	3.95 kg	9.30 lb	4.22 kg	
L16	3.960	100.6	3.960	100.6	3.960	100.6	3.960	100.6	
L17	1.06	27.1	1.06	27.1	1.06	27.1	1.06	27.1	

L14 = WEIGHT ADDER FOR GRR12

L15 = WEIGHT ADDER FOR GRR02 & GRR22

NOTES:

1) LOCKING FORCE INDICATED IS THE ACTUAL LOCKING FORCE WITH A DRY, CLEAN ROD AND DOES NOT INCLUDE ANY SAFETY FACTOR. IT IS POSSIBLE TO OVERRIDE THE RODLOK WITH VERY HIGH FORCE APPLIED TO THE GRIPPER. STATIC LOCKING FORCE MAY BE INCREASED ON SYNCHRONIZED UNITS, GRR12, WITH THE ADDITION OF A SECOND RODLOK. SEE KITS BELOW.

	STATIC LOCKING FORCE					
	(see Note 1)					
SIZE	lb	N				
63	495	2200				

RODLOK SEAL KIT (PER JAW)

Full unit description - H9115

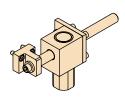
Kit includes seals and wear rings for a

single (1) jaw.

- 2) CIRCLED NUMBERS INDICATE POSITION.
- 3) *1/8" NPT PORT IS AN ADAPTOR INCLUDED WITH IMPERIAL UNITS.

ACCESSORIES - RODLOK

The Series GRR is -H47 ready as standard. The following items may be added to the Design 2 [6] GRR or may be used as replacement parts. Note that the kits below are for one jaw only.





COMPLETE RODLOK KIT (PER JAW)

Full unit description - H9110

Kit includes Rodlok and Rodlok adaptor for a single (1) jaw.

RODLOK ADAPTOR KIT (PER JAW)

Full unit description - H9105

Kit includes Rodlok adaptor for a single (1) jaw. Does not include Rodlok.

RODLOK KIT (PER JAW)

Full unit description - H9100

Kit includes Rodlok for a single (1) jaw. Does not include Rodlok imperial port adaptor.





SPP99

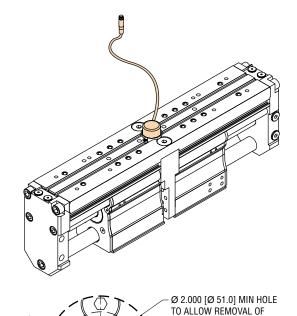
JAW POSITION SENSOR

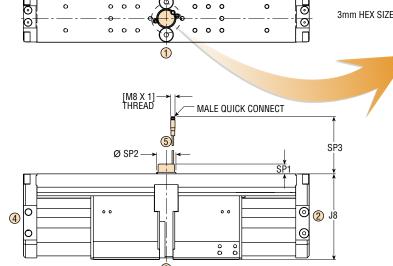
Provides an easy to use, economical, fully integrated solution to continuously monitor the grip position of the jaws. The sensor mounts directly to the gripper making field installation or replacement quick and easy. The 3-pin quick-connect connector provides a 0-10 volt analog output compatible with standard analog control modules. Consult PHD for use with -V1 option.



COUPLED JAW POSITION SENSOR

Has the same functional performance as the -SPP99 option, except it is mechanically coupled and **must be specified when the order is placed**. This option cannot be added to the unit at a later time.





LETTER	MODEL NUMBER GRRx2-x-63	
DIM	in	mm
J8	6.375	161.9
SP1	.748	19.0
SP2	1.437	36.5
SP3	10.000	254

POSITION SENSOR

Ø 1.500 [Ø 38.1] MIN HOLE TO PROVIDE CLEARANCE FOR POSITION SENSOR

+ VDC (PIN 1)

GROUND (PIN 3)

SIGNAL OUT (PIN 2)

RESOLUTION

Resolution of sensor installed into gripper is 0.001 inch [0.025 mm] in conjunction with an analog control module having 15 bits or greater input resolution.

REPEATABILITY

Maximum variation of reported grip dimension when repeatedly gripping the same object is ±0.002 in [±0.05 mm].

ENVIRONMENTAL

Temperature Limits: -20 to 180°F [-28 to 82°C] IP67 compliant when installed in gripper.

ELECTRICAL

Supply Voltage: 15-30 VDC, reverse polarity protected Output Voltage: 0-10 VDC, short-circuit protected Output Constant: 663 ± 1mV/inch [26.10 ± 0.04 mV/mm] of

grip change

Output Voltage Offset: <10mV typical

CONNECTOR INTERFACE

Output Linearity: ± 0.3%



PHDV1

ACCESSORIES: SERIES GRR GRIPPERS



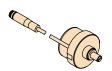
SPP99 JAW POSITION SENSOR

Series GRR is supplied -SPP99 ready. Kit below provides the same jaw position sensor and mounting hardware supplied preassembled with the -SPP99 option. See option details for further information.

SPP99 JAW POSITION SENSOR KITS

KIT	STANDARD	CORROSION RESISTANT
Sensor Replacement Kit	74209-31	74209-32

Kit includes 1 jaw position sensor, 2 mounting screws, 1 seal and 1 coupling seal



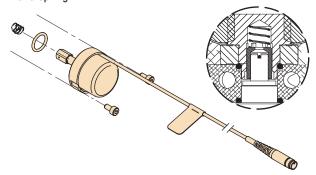
STT99 JAW POSITION SENSOR

Kits below provide the same jaw position sensor and mounting hardware supplied pre-assembled with the -STT99 option. See option details for further information.

REPLACEMENT STT99 JAW POSITION SENSOR KITS

KIT	STANDARD	CORROSION RESISTANT
Sensor Replacement Kit	84404-11	84404-12

Kit includes 1 jaw position sensor, 2 mounting screws, 1 seal and spring



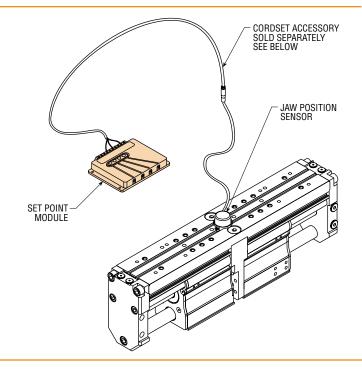
SET POINT MODULE

Set Point Module converts analog output from sensor into discrete on-off outputs. Module provides four independently adjustable set points throughout jaw travel. Available with NPN (sink) or PNP (source) outputs.

SET POINT MODULE

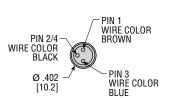
PART NO.	DESCRIPTION
9800-01-0300	
9800-01-0400	4.5-24 VDC, Source Type Output

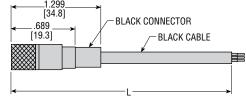
See Switches and Sensors section in main catalog for more information.



CORDSET

Provides a cordset with female quick connect and additional cable. Perfect for use with the Set Point Module.





	LETTER DIM.
MODEL NO.	L
63549-02	78.74 [2 m]
63549-05	196.85 [5 m]

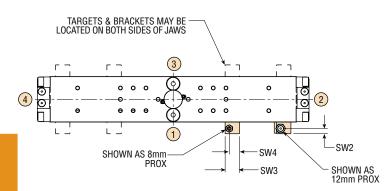


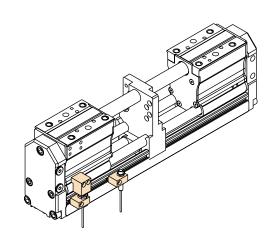


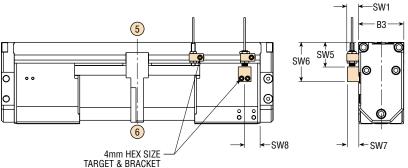
PROXIMITY SWITCHES - EXTERNAL

This accessory provides for the external mounting of 8 or 12 mm threaded round metal sensing inductive proximity switches. Multiple switches may be mounted using multiple brackets. Proximity switches, targets, and mounting brackets are ordered separately. See the Switches and Sensors section for complete switch specifications.

NOTE: Target and bracket kits do not interchange with Series 1 [5] GRR Grippers.







DIM	GRRx2-x-63	
LETTER	in	mm
В3	3.544	90.0
SW1	.920	23.4
SW2	.410	10.4
SW3	1.125	28.6
SW4	.852	21.6
SW5	1.920	48.8
SW6	3.080	78.2
SW7	.900	22.9
SW8	1.211	30.8



8 mm THREADED INDUCTIVE PROXIMITY SWITCHES

PART NUMBER	DESCRIPTION
51422-005-02	NPN (Sink), 2 meter cable
51422-006-02	PNP (Source), 2 meter cable



12 mm THREADED INDUCTIVE PROXIMITY SWITCHES

PART NUMBER	DESCRIPTION
15561-001	NPN (Sink), 2 meter cable
15561-002	PNP (Source), 2 meter cable
15561-003	VAC Solid State, 3 meter cable



8 mm & 12 mm THREADED INDICTIVE PROXIMITY SWITCH TARGET KITS

O IIIII Q 12 IIIII TIIIEADED INDOOTIVET HOXIIIITT OWITON TANGET KITO	
STANDARD	CORROSION RESISTANT
74994-31	74994-32

Kit includes 1 proximity switch target and 2 target mounting screws



THREADED INDUCTIVE PROXIMITY SWITCH MOUNTING BRACKET KITS

8 mm	CORROSION RESISTANT	12 mm	CORROSION RESISTANT
SWITCH	8 mm SWITCH	SWITCH	12 mm SWITCH
74992-31	74992-32	74993-31	74993-32

Kit includes 1 proximity switch mounting bracket, 1 mounting nut, and 1 mounting screw

All dimensions are reference only unless specifically toleranced.



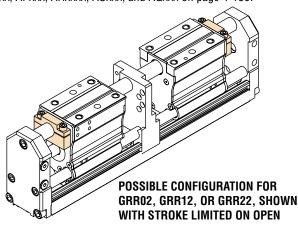


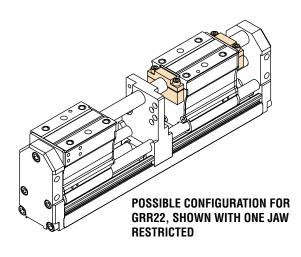
PHDV1

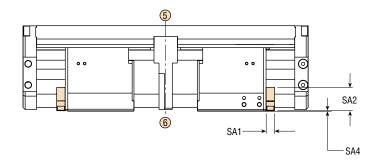


TRAVEL ADJUSTMENT COLLARS

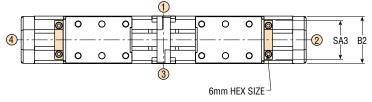
This accessory provides travel adjustment stop collars for use in limiting jaw travel on open or close. The travel adjustment stop collars provide infinite adjustment. Synchronized model (GRR12) requires travel adjustment collars to be identically located for both jaws, in the same direction of travel. Non-synchronized models (GRR02 & GRR22) do not require identical stop locations for each jaw. For non-adjustable jaw travel limiting, see options ANxxx, ATxxx, APxxx, ARxxxx, AUxxx, and AQxxx on page 4-139.

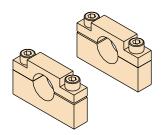






DIM		GRRx2-x-63	
LETTE	R	in	mm
B2		3.500	88.9
SA1		.630	16.0
SA2		1.740	44.2
SA3		2.900	73.7
SA4		.035	.9





STROKE ADJUSTMENT COLLAR KITS		
STANDARD	CORROSION RESISTANT	
74211-01	74211-02	

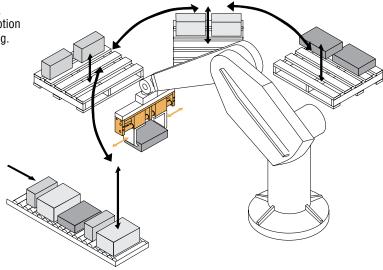
Kit includes 2 stroke adjustment collars and 4 mounting screws.





GRIPPER FOR LONG TRAVEL, HIGH FORCE CAPABILITY

The Series GRR Gripper is designed for long stroke, high force applications. The synchronized parallel jaw motion automatically centers items for operations such as sorting. The long stroke compensates for items of varying size or position.



GRIPPER FOR HIGH FORCE AND HIGH JAW LOADS

The Series GRR Gripper is designed to withstand external forces when moving heavy parts quickly. The parallel design provides for automatic centering of parts, while the long jaw travel makes it flexible for a wide variety of applications. In this application, two Series GRR Grippers are mounted on a fixture attached to a robot. The robot will transfer rims from an in-feed conveyor station to and from three separate machining processes. Then the finished rim is placed on a conveyor, taking it from the machining area.

